

Extra stuff for Hansens RBC model

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1 Additional material for the RBC model

Constructing an RBC model (log-linear version)

- Write out model
 - Optimization problem of households
 - * First order conditions
 - * Budget constrains
 - Optimization problem of firms
 - * First order conditions
 - * Budget constrains
 - Optimization problem of other agents
 - * Government
 - * Financial intermediaries
 - Aggregation conditions
 - Equilibrium conditions
- Find stationary state
- Log-linearize model around stationary state
- Solve linear version for linear plans
- Analyze second moments of model

Hansen's basic model

- Robinson Crusoe maximizes the discounted utility function

$$\max \sum_{t=0}^{\infty} \beta^t u(c_t, l_t)$$

- The specific utility functions

$$u(c_t, 1 - h_t) = \ln c_t + A \ln(1 - h_t)$$

with $A > 0$.

- The production function is

$$f(\lambda_t, k_t, h_t) = \lambda_t k_t^\theta h_t^{1-\theta}$$

- λ_t is a random technology variable that follows the process

$$\lambda_{t+1} = \gamma \lambda_t + \varepsilon_{t+1}$$

for $0 < \gamma < 1$. ε_t iid, positive, bounded above, $E\varepsilon_t = 1 - \gamma$.

– $\implies E \lambda_t$ is 1 and $\lambda_{t+1} > 0$.

Hansen's basic model (continued)

- Capital accumulation follows the process

$$k_{t+1} = (1 - \delta)k_t + i_t$$

- The feasibility constraint is

$$f(\lambda_t, k_t, h_t) \geq c_t + i_t$$

Log linear version of Hansen's model

- The five equations of the Hansen model are (adjusted)

$$\begin{aligned} 1 &= \beta E_t \left[\frac{C_t}{C_{t+1}} (r_{t+1} + (1 - \delta)) \right] \\ AC_t &= (1 - \theta) (1 - H_t) \frac{Y_t}{H_t} \\ C_t &= Y_t + (1 - \delta)K_t - K_{t+1} \\ Y_t &= \lambda_t K_t^\theta H_t^{1-\theta} \\ r_t &= \theta \frac{Y_t}{K_t} \end{aligned}$$

Log-linearization (Uhlig's method)

- Define the log difference of each variable as

$$\tilde{X}_t = \ln X_t - \ln \bar{X}$$

- Then the original variable is

$$X_t = \bar{X} e^{\tilde{X}_t}$$

- Substitute this into each equation (here a production function)

$$Y_t = \lambda_t K_t^\theta H_t^{1-\theta}$$

- becomes

$$\bar{Y} e^{\tilde{Y}_t} = e^{\tilde{\lambda}_t} \bar{K}^\theta e^{\theta \tilde{K}_t} \bar{H}^{(1-\theta)} e^{(1-\theta)\tilde{H}_t}$$

Log-linearization (Uhlig's method) continued

- Because $\bar{Y} = \bar{K}^\theta \bar{H}^{(1-\theta)}$, this simplifies to

$$e^{\tilde{Y}_t} = e^{\tilde{\lambda}_t + \theta \tilde{K}_t + (1-\theta)\tilde{H}_t}$$

and, using the approximation $e^{\tilde{X}_t} \approx 1 + \tilde{X}_t$, if \tilde{X}_t is small, this equals

$$1 + \tilde{Y}_t = 1 + \tilde{\lambda}_t + \theta \tilde{K}_t + (1 - \theta) \tilde{H}_t$$

and

$$\tilde{Y}_t = \tilde{\lambda}_t + \theta \tilde{K}_t + (1 - \theta) \tilde{H}_t$$

- Recall the direct method: we got

$$\frac{Y_t}{\bar{Y}} + 1 \approx \frac{\lambda_t}{\bar{\lambda}} + \frac{\theta K_t}{\bar{K}} + \frac{(1-\theta) H_t}{\bar{H}}$$

- write as

$$\frac{\bar{Y} e^{\tilde{Y}_t}}{\bar{Y}} + 1 \approx \frac{\bar{\lambda} e^{\tilde{\lambda}_t}}{\bar{\lambda}} + \frac{\bar{K} \theta e^{\tilde{K}_t}}{\bar{K}} + \frac{\bar{H} (1-\theta) e^{\tilde{H}_t}}{\bar{H}}$$

- or

$$e^{\tilde{Y}_t} + 1 \approx e^{\tilde{\lambda}_t} + \theta e^{\tilde{K}_t} + (1-\theta) e^{\tilde{H}_t}$$

- which is approximately

$$\left(1 + \tilde{Y}_t\right) + 1 \approx \left(1 + \tilde{\lambda}_t\right) + \theta \left(1 + \tilde{K}_t\right) + (1 - \theta) \left(1 + \tilde{H}_t\right)$$

- or

$$\tilde{Y}_t \approx \tilde{\lambda}_t + \theta \tilde{K}_t + (1 - \theta) \tilde{H}_t$$

Another example

- Consider (a first order condition of the Hansen model)

$$1 = \beta E_t \left[\frac{C_t}{C_{t+1}} (r_{t+1} + (1 - \delta)) \right]$$

$$\begin{aligned} 1 &= \beta E_t \left[\frac{\bar{C} e^{\tilde{C}_t}}{\bar{C} e^{\tilde{C}_{t+1}}} \bar{r} e^{\tilde{r}_{t+1}} + (1 - \delta) \frac{\bar{C} e^{\tilde{C}_t}}{\bar{C} e^{\tilde{C}_{t+1}}} \right] \\ &= \beta E_t \left[\bar{r} e^{\tilde{C}_t - \tilde{C}_{t+1} + \tilde{r}_{t+1}} + (1 - \delta) e^{\tilde{C}_t - \tilde{C}_{t+1}} \right] \\ &\approx \beta \left(\bar{r} E_t \left[1 + \tilde{C}_t - \tilde{C}_{t+1} + \tilde{r}_{t+1} \right] + (1 - \delta) \left[1 + \tilde{C}_t - \tilde{C}_{t+1} \right] \right) \\ &= E_t \left[1 + \tilde{C}_t - \tilde{C}_{t+1} + \beta \bar{r} \tilde{r}_{t+1} \right], \end{aligned}$$

or (after cancelling the 1's and cleaning up the expectations)

$$0 \approx \tilde{C}_t - E_t \tilde{C}_{t+1} + \beta \bar{r} E_t \tilde{r}_{t+1}$$

Another example

- The household budget constraint

$$C_t = Y_t + (1 - \delta)K_t - K_{t+1}$$

- Becomes

$$\bar{C} e^{\tilde{C}_t} = \bar{Y} e^{\tilde{Y}_t} + (1 - \delta) \bar{K} e^{\tilde{K}_t} - \bar{K} e^{\tilde{K}_{t+1}}$$

- and this is approximately

$$\bar{C} (1 + \tilde{C}_t) = \bar{Y} (1 + \tilde{Y}_t) + (1 - \delta) \bar{K} (1 + \tilde{K}_t) - \bar{K} (1 + \tilde{K}_{t+1})$$

- Given the stationary state, this reduces to

$$\bar{C} \tilde{C}_t = \bar{Y} \tilde{Y}_t + (1 - \delta) \bar{K} \tilde{K}_t - \bar{K} \tilde{K}_{t+1}$$

Another example

- The second first order condition from the Hansen model

$$AC_t = (1 - \theta) (1 - H_t) \frac{Y_t}{H_t}$$

- Bring H_t over to the left hand side and expand the right hand side

$$AC_t H_t = (1 - \theta) Y_t - (1 - \theta) H_t Y_t$$

- Put in the log-linear expression

$$AC\bar{H}e^{\tilde{C}_t + \tilde{H}_t} = (1 - \theta) \bar{Y} e^{\tilde{Y}_t} - (1 - \theta) \bar{H} \bar{Y} e^{\tilde{H}_t + \tilde{Y}_t}$$

- Approximate

$$\begin{aligned} AC\bar{H} \left(1 + \tilde{C}_t + \tilde{H}_t \right) &= (1 - \theta) \bar{Y} \left(1 + \tilde{Y}_t \right) \\ &\quad - (1 - \theta) \bar{H} \bar{Y} \left(1 + \tilde{H}_t + \tilde{Y}_t \right) \end{aligned}$$

- Using conditions from the stationary state this simplifies to

$$AC\bar{H} \left(\tilde{C}_t + \tilde{H}_t \right) = (1 - \theta) \bar{Y} \tilde{Y}_t - (1 - \theta) \bar{H} \bar{Y} \left(\tilde{H}_t + \tilde{Y}_t \right)$$

- Rearranging this becomes

$$AC\bar{H} \tilde{C}_t = (1 - \theta) \bar{Y} (1 - \bar{H}) \tilde{Y}_t - \bar{H} [(1 - \theta) \bar{Y} + AC\bar{C}] \tilde{H}_t$$

- which can be further simplified (because $[(1 - \theta) \bar{Y} + AC\bar{C}] \bar{H} = (1 - \theta) \bar{Y}$) to

$$\frac{AC\bar{H}}{(1 - \theta) \bar{Y}} \tilde{C}_t = (1 - \bar{H}) \tilde{Y}_t - \tilde{H}_t$$

- and again (because $\frac{AC\bar{H}}{(1 - \theta) \bar{Y}} = 1 - \bar{H}$) to

$$\tilde{C}_t = \tilde{Y}_t - \frac{\tilde{H}_t}{(1 - \bar{H})}$$

How to handle a problematic equation

- An equation of the form

$$Y_t = \sum_{i=0}^{\infty} \beta^i \frac{Z_{t+i}}{1 - Z_{t+i}}$$

does not let you bring the $1 - Z_{t+i}$ part over to the other side

- Need to do a number of approximations

$$\begin{aligned} \frac{Z_{t+i}}{1 - Z_{t+i}} &= \frac{\bar{Z} e^{\tilde{Z}_{t+i}}}{1 - \bar{Z} e^{\tilde{Z}_{t+i}}} \approx \frac{\bar{Z} (1 + \tilde{Z}_{t+i})}{1 - \bar{Z} (1 + \tilde{Z}_{t+i})} \\ &= \frac{\bar{Z}}{1 - \bar{Z}} \frac{1 + \tilde{Z}_{t+i}}{\left(1 - \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i} \right)} \end{aligned}$$

- But

$$\left(1 - \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i}\right) \approx e^{-\frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i}}$$

- So the equation can be written as

$$\begin{aligned} &= \frac{\bar{Z}}{1 - \bar{Z}} \left(1 + \tilde{Z}_{t+i}\right) e^{\frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i}} \\ &= \frac{\bar{Z}}{1 - \bar{Z}} \left(1 + \tilde{Z}_{t+i}\right) \left(1 + \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i}\right) \\ &= \frac{\bar{Z}}{1 - \bar{Z}} \left(1 + \tilde{Z}_{t+i} + \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i} + \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i} \tilde{Z}_{t+i}\right) \\ &= \frac{\bar{Z}}{1 - \bar{Z}} \left(1 + \tilde{Z}_{t+i} + \frac{\bar{Z}}{1 - \bar{Z}} \tilde{Z}_{t+i}\right) \\ &= \frac{\bar{Z}}{1 - \bar{Z}} \left(1 + \frac{1}{1 - \bar{Z}} \tilde{Z}_{t+i}\right) \end{aligned}$$

- So

$$\begin{aligned} \bar{Y} \left(1 + \tilde{Y}_t\right) &= \frac{\bar{Z}}{1 - \bar{Z}} \sum_{i=0}^{\infty} \beta \left(1 + \frac{1}{1 - \bar{Z}} \tilde{Z}_{t+i}\right) \\ &= \frac{\bar{Z}}{(1 - \bar{Z})(1 - \beta)} + \frac{\bar{Z}}{(1 - \bar{Z})^2} \sum_{i=0}^{\infty} \beta^i \tilde{Z}_{t+i} \end{aligned}$$

- stationary state of $Y_t = \sum_{i=0}^{\infty} \beta^i \frac{Z_{t+i}}{1 - Z_{t+i}}$ is $\bar{Y} = \frac{\bar{Z}}{(1 - \bar{Z})(1 - \beta)}$, so this becomes

$$\tilde{Y}_t = \frac{(1 - \beta)}{(1 - \bar{Z})} \sum_{i=0}^{\infty} \beta^i \tilde{Z}_{t+i}$$